2500V/µs Slew Rate Op Amps Process Large Signals with Low Distortion at High Frequencies by Kris Lokere and Glen Brisebois

Introduction

The LT1818 and LT1819 are low distortion single and dual operational amplifiers that offer 400MHz gain bandwidth product and $2500V/\mu s$ slew rate. The parts operate with supplies from $\pm 2V$ to $\pm 6V$ and draw a typical supply current of only 9mA per amplifier.

The amplifiers can drive 100 Ω loads with a low distortion of -85dBc relative to a 5MHz, $2V_{P-P}$ signal. In single 5V supply applications, the output swings to 0.8V from either supply rail with a 500 Ω load (to 2.5V), and to 1.0V with a 100 Ω load. The output current drive capability is typically 70mA. The low distortion and good output drive capability, combined with the 6nV/ \sqrt{Hz} input voltage noise, make the LT1818/LT1819 an ideal choice for a wide variety of applications.

The LT1818 and LT1819 are available in space saving packages: the LT1818 single op amp in an SOT23-5; the LT1819 dual op amp in an 8-lead MSOP. Both parts are also available in an easy to use 8-lead SOIC. All parts are fully specified at ±5V and single 5V supplies, and are available in commercial and industrial temperature grades.

Table 1 summarizes the performance specifications of the LT1818 and LT1819.



Figure 1. Test circuit for LT1818 (or competitor's part) configured in gain of -1.



Figure 2a. The LT1818 responds to a 20MHz, $\pm 4V$ input pulse with a fast enough slew rate to retain the shape of the pulse

Fast Slew Rate Preserves High Bandwidth for Large Signals

The LT1818/LT1819 amplifiers exhibit an ultrafast slew rate of 2500V/ μ s in a gain of +1 and 1800V/ μ s in a gain of -1. The importance of a high slew rate is demonstrated by comparing the large signal dynamic response of amplifiers with similar bandwidths but differing slew rates. We compared the LT1818 to a competitor's ampli-



Figure 2b. Competitor's 625MHz op amp responds to the same input with inadequate slew rate to maintain pulse integrity

fier, which has a wider, 625MHz bandwidth, but only a 400V/ μ s slew rate. Figure 1 shows a test circuit for a device configured in an inverting gain (A_V = -1). Figures 2a and 2b show the step response to a 20MHz, ±4V input pulse. The 3.5ns rise/fall time of the LT1818 (consistent with a 1800V/ μ s slew rate) preserves the 20MHz step very well. The lower slew rate amplifier, in contrast, is only barely fast enough to transmit the waveform,

Table 1: LT1818/LT1819 performance summary (all specifications are typical with $\pm 5V$ supplies and 25°C unless otherwise noted)

Parameter	Value
Gain Bandwidth Product	400MHz
Slew Rate	2500V/µs
Supply Current (per Amplifier)	9mA
Harmonic Distortion (5MHz, $2V_{P-P}$, R_L =100 Ω)	-85dBc
Input Noise Voltage	6nV/√Hz
Input Noise Current	1.2pA/√Hz
Input Offset Voltage (Max)	1.5mV
Input Bias Current (Max)	±8µA
Input Common Mode Range	±4.2V
Output Voltage Swing (R_L =500 Ω)	±4.1V
Settling Time (5V, $\pm 0.1\%$)	9ns

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Figure 3b. Competitor's 625MHz response to the same sine wave is distorted.

turning it into a triangle wave. The difference in slew rate also has important ramifications for distortion of sine waves. Figures 3a and 3b show the response of both amplifiers to a 50MHz, $4V_{P-P}$ sine wave. The LT1818 transmits the waveform with minimal distortion, but the competitor's part turns the sine wave into a triangle wave, a result of the lower slew rate. This demonstrates that, to accurately process real world signals, slew rate is often the limiting parameter rather than bandwidth.



Figure 4. Dual op amp cascaded to form a gain of 10 (20dB).

The application shown in Figure 4 demonstrates the excellent high-frequency response of the LT1819 dual amplifier, and how two op amps can be combined to further increase bandwidth. The circuit shows the dual LT1819 op amp configured as two cascaded gain stages that together form a gain of 10 (= 20dB). The feedback capacitor on the second stage serves to cancel a pole formed by the feedback resistors and the input capacitance, to reduce peaking and ringing. The frequency-domain response (Figure 5) shows the -3dB frequency at 80MHz, which represents a gain-bandwidth product of 800MHz, consistent with two 400MHz amplifiers in series. Figure 6 shows the transient response to a small step. The 3.5ns rise/fall time is consistent with an 80MHz-3dB bandwidth. Figure 7 shows that the step response is only a little slower making a transition to a full $6V_{P-P}$, showing the merits of a high slew rate.

Low Distortion ADC Driver

Figure 8 illustrates the use of the LT1818 as a buffer for the LTC1744 14-Bit 50Msps ADC. The amplifier must provide low noise, low distortion as well as fast settling characteristics in order to recover quickly from the sampling loading effects of the ADC. The LTC1744 signal-to-noise ratio (SNR) of 73.5dB at $2V_{P-P}$ implies an input referred noise of $149\mu V_{RMS}$. The $6nV/\sqrt{Hz}$ input voltage noise of the LT1818, integrated over a 94MHz bandwidth (formed by the 51.1Ω , 18 pFand the $C_{\rm IN}$ of the ADC) results in only $91\mu V_{RMS}$ of input noise. The contribution of the input referred current noise of the LT1818 depends on the source resistance of the circuit that drives the LT1818. For a 1k source resistance, the $1.2pA/\sqrt{Hz}$ input current noise results in $18\mu V_{RMS}$ over the same bandwidth. Both noise sources taken together still do not degrade the noise performance of the 14-bit ADC. Figure 9 shows the 4096 bin FFT of the converter output. This implies a full scale SNR of 76dB, just slightly better than the ADC's typical 73.5dB specification. More readily seen in the FFT is the SFDR of 78dB.

You can further improve the performance of the circuit by using the two amplifiers of the LT1819 to convert the single-ended input signal to a differential signal and drive both inputs of the LTC1744, as shown in Figure 10. An advantage of driving the ADC differentially is that the signal swing at each input can be reduced, which reduces the distortion of both the ADC and the amplifier. Typical performance is shown in the



Figure 5. Frequency-domain response of 20dB gain block



Figure 6. Small-signal transient response of 20dB gain block



rigure 7. Large-signal transient response of 20dB gain block





Figure 8. Single ended ADC driver



Figure 10. Single-to-differential ADC driver

FFT of Figure 11, again consisting of 4096 bins derived from 8192 samples.

Fast Edge Generation to Measure Slew Rate

A 2500V/ μ s slew rate implies that the transition between $\pm 2V$ occurs in 1.6ns. In order to accurately measure slew rates this fast, it is necessary to generate an input step that is faster than the device-under-test. Many off-the-shelf function generators fail in this regard, in which case custommade circuitry may be necessary. The widely used HP8110A 100MHz Pulse Generator, for example, has a minimum rise/fall time of 1.8ns, which fails to provide a fast enough stimu-



Figure 12. A simple inverter used to generate a sharp pulse—fast but too little signal swing and output drive

lus for this test. The older HP8082A Pulse Generator provides 1ns transitions, but its output amplitude is only 5V into 50Ω , which limits its flexibility to drive the amplifier on $\pm 5V$ supplies.

The simple circuit of Figure 12 uses a high-speed inverter such as the NC7SZU04. Since the inverter has high gain, it sharpens the input edge of whatever pulse generator is used to drive it. The output is AC coupled to level shift the single sup-



Figure 9. FFT of single ended ADC driver



figure 11. FFT of single-to differential ADC driver

ply inverter output to drive a split supply biased op amp. This inverter can provide rise and fall times as fast as 0.8ns, but the maximum supply voltage (and hence the maximum swing) is 5.5V, which is just short of the ±3V or ±4V desired for full range slew rate testing of the LT1818/ LT1819. In addition, the 16mA output current drive of the inverter precludes a 50Ω termination, which limits the universal applicability of this circuit.



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Figure 14. Output of pulse-sharpener circuit

Figure 13 shows a more involved, but very flexible and fast solution. The diode bridge D1-D4 switches the LT1210 current-feedback amplifier, which runs off ± 15 V supplies. This way, the input edge does not need to swing more than ± 1 V, and the current into the inverting node of the LT1210 switches very quickly. The already fast waveform at the output of the amplifier is then AC coupled into the D5–D6 Step Recovery Diodes (SRD).

An SRD is a two terminal p-i-n junction whose DC characteristics are similar to the usual p-n junction diode, but whose switching characteristics are quite different. The most distinguishing feature of the SRD is the very abrupt dependence of its junction impedance upon its internal charge storage. If a forward biased SRD is suddenly reverse-current biased, it will first appear as a very low impedance until the stored charge is depleted. Then the impedance will suddenly increase to its normal high reverse value, thereby stopping the flow of reverse current. This impedance transition generally takes only a few hundred picoseconds. The circuit in Figure 13 uses this SRD property as a pulse sharpener, generating a sub-one-nanosecond edge at the output. You can set the voltage levels of the output waveform by adjusting $\pm V_2$. Figure 14 shows a 5V, 0.8ns output waveform generated by this circuit.

Finally, an important consideration in these measurements is the bandwidth of the oscilloscope used. The photograph in Figure 14 is taken with a Tektronix TDS820 6GHz digitizing oscilloscope. For a detailed description of the effect of slower oscilloscopes on measuring fast edges, refer to Linear Technology Application Note 47.

LT1818 Circuit Design

A simplified schematic of the LT1818/ LT1819 is shown in Figure 15. Both inputs are high impedance, classifying the amplifier as a voltage feedback topology. Complementary NPN and PNP emitter followers Q1-Q8 buffer each input and present the differential input signal across the internal resistor R1. The input common mode range extends to typically 0.8V from either supply, and is limited by a V_{BE} of Q10/Q14 plus a V_{SAT} of Q5/Q6. NPN and PNP current mirrors Q10– Q11 and Q14–Q15 mirror the current generated through R1 into the high impedance node. Cascode devices Q9 and Q13 raise the output impedance of the mirror, improving the open loop gain.

Resistor R1, the transconductances of Q5-Q8, and the compensation capacitor C1 set the 400MHz gain bandwidth product of the amplifier. The R_C , C_C network between the high impedance node and the output provides extra compensation when the output drives a capacitive load. This keeps the LT1818/LT1819 unity-gain stable with a C_{LOAD} up to 20pF. The amplifier can drive larger capacitive loads when configured in higher noise gains, or with an isolation resistor of 10Ω to 50 Ω in series with the load. The R_2 , C_2 networks on the current mirrors provide a pole and zero at a frequency below the unity-gain frequency. This lowers the frequency where the open loop gain crosses 0dB, which improves the phase margin of the amplifier while maintaining a high open loop gain at lower frequencies.

The current generated across R1, divided by the capacitor C1, determines the slew rate. Note that this current, and hence the slew rate, are proportional to the magnitude of the input step. The input step equals the output step divided by the closed loop gain. The highest slew rates are there-



Figure 15. Simplified schematic of LT1818/LT1819 amplifier

fore obtained in the lowest gain configurations. The 2500V/ μ s slew rate specified on the data sheet is measured in a noninverting unity gain configuration. The 1800V/ μ s production tested slew rate is measured in an (inverting) gain of –1, which is equivalent to a noninverting gain of 2.

The internal current generated across the input resistor can be much higher than the quiescent supply current (up to 80mA). In normal transient closed loop operation this does not present a problem, since after a few nanoseconds the feedback brings the differential input signal back to zero. However, sustained (i.e. open loop) differential input voltages may result in excessive power dissipation and therefore this amplifier should not be used as a comparator.

The output stage buffers the high impedance node from the load by providing current gain. Emitter followers Q17-Q20 provide a current gain equal to $Beta_{NPN} \times Beta_{PNP}$, but the effective current gain is greatly enhanced by the dynamic base current compensation provided by Q24-Q26 and Q21-Q23. Q24 measures a fraction of the output current that flows through Q19, and mirror Q25-Q26 injects the appropriate current back into the base of Q19. This signal-dependent boost improves the linearity of the amplifier by reducing the amount of differential input signal required for a given output current. An additional advantage is that the output devices can be smaller, which requires less quiescent current for a given amplifier speed.

Conclusion

The ultrafast slew rate and high bandwidth allow the LT1818 and LT1819 op amps to process large signals at high frequencies with low distortion. Combined with the low noise and moderate supply current, these amplifiers are a good choice for receivers, filters, or drivers of cables and ADCs in high-speed communication or data acquisition systems.